



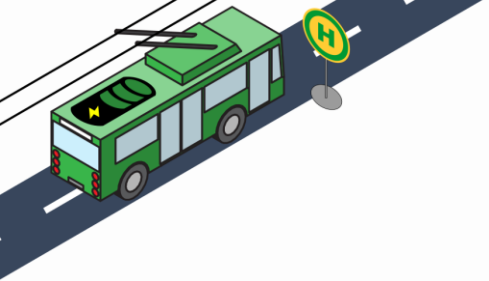
# Presentation of the BOB (battery-overhead-bus) project – innovations for smart trolleybus networks

University of Wuppertal  
Institute of Power System Engineering  
Univ.-Prof. Dr.-Ing. M. Zdrallek  
Research Group:  
Smart Grids and Smart Systems

Dirk Baumeister (Research Assistant)

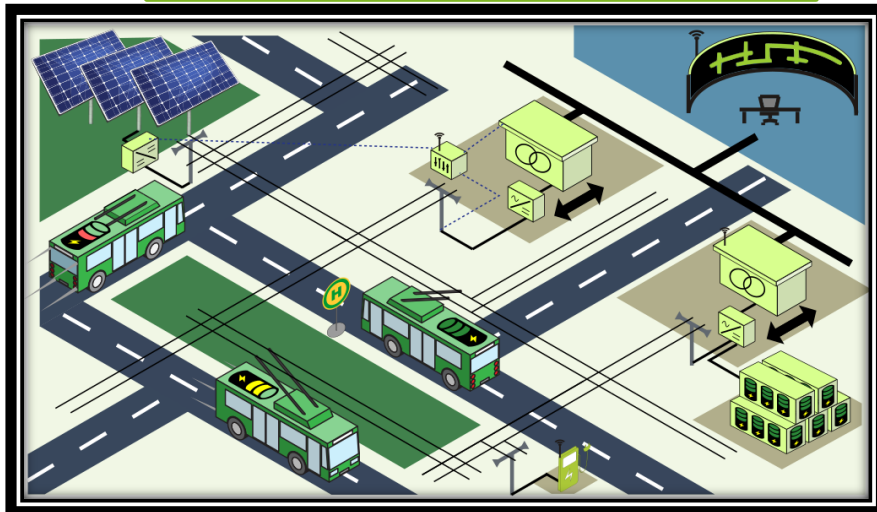
**Trolley 2.0 Partner Meeting and 1<sup>st</sup> User Forum**



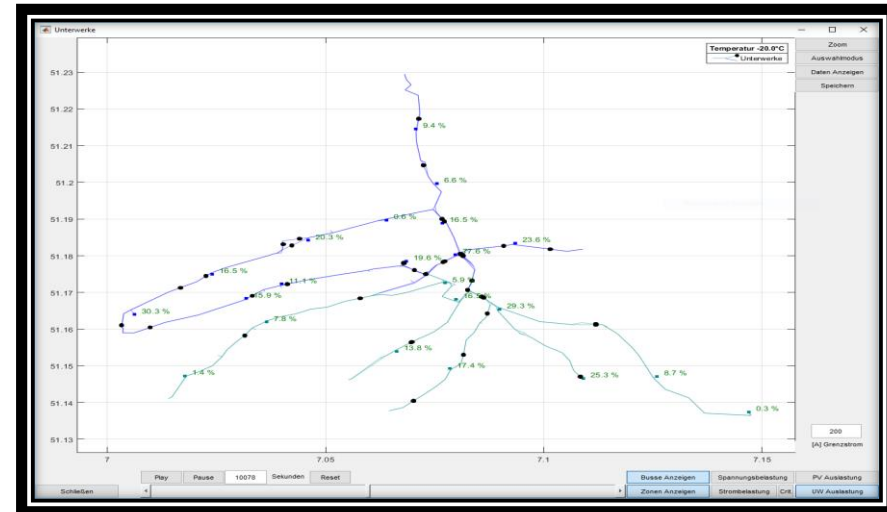


# Structure

## Status Quo & Project “BOB Solingen”



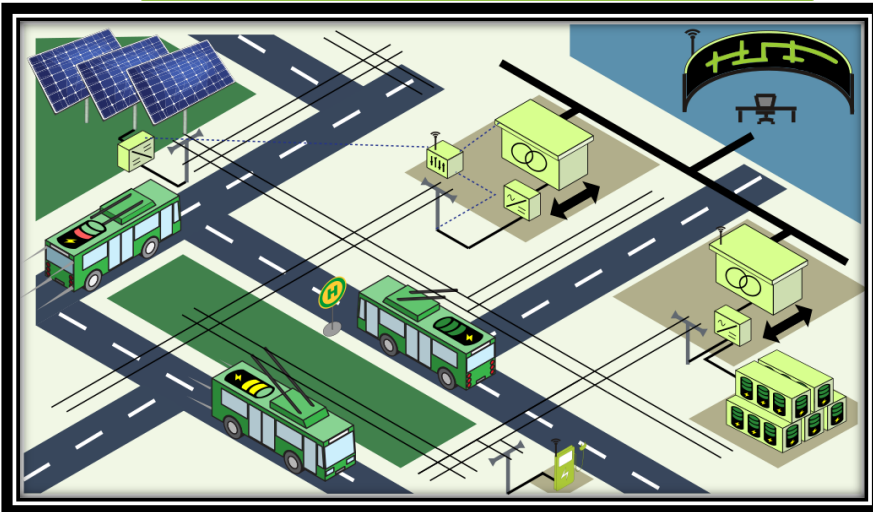
## Goal Realization



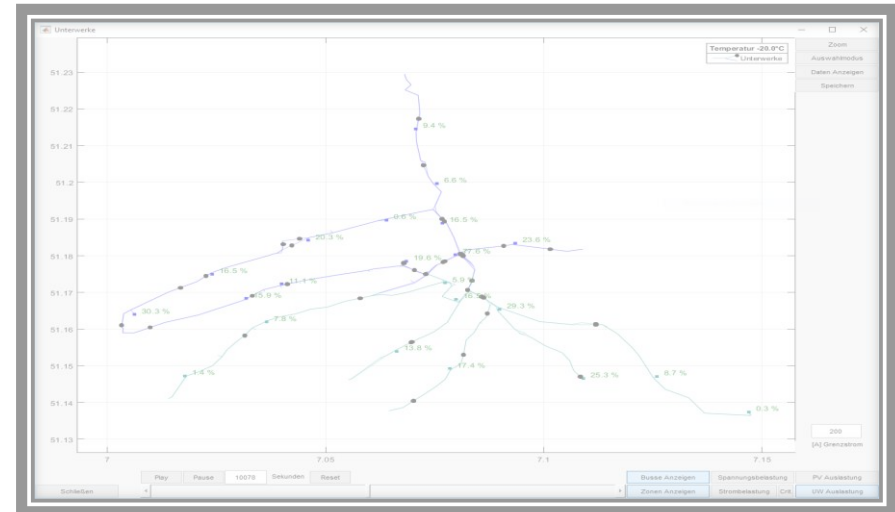


# Structure

## Status Quo & Project “BOB Solingen”



## Goal Realization

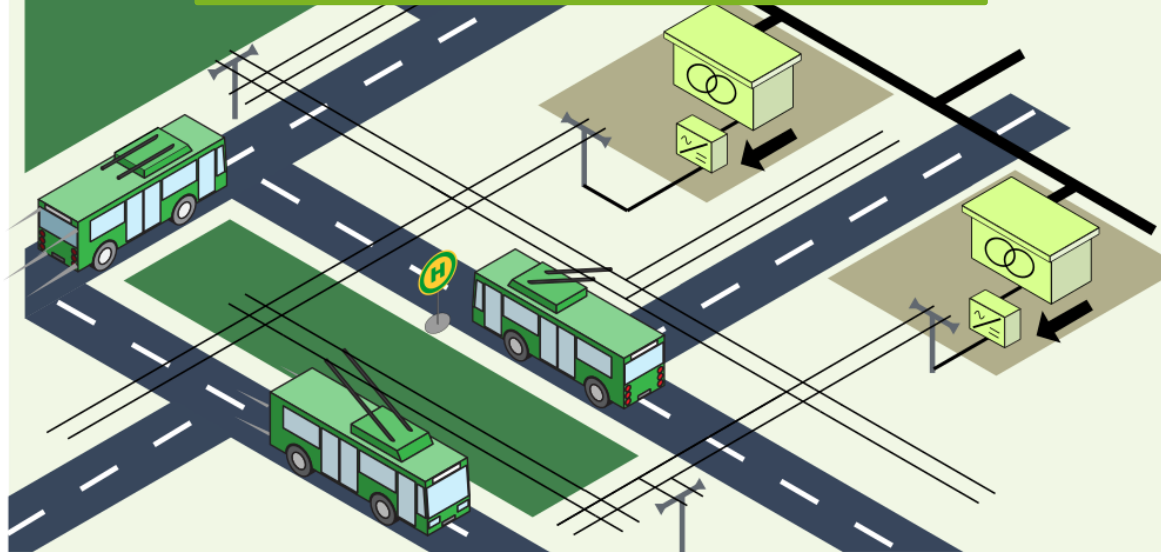


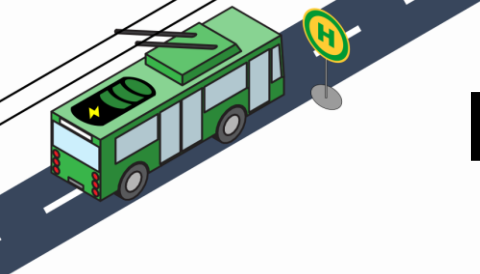


# Status Quo

- Solingen owns a trolleybus system with 50 electrically powered trolleybuses containing auxiliary diesel engines
- Lines with partly uncovered power supply have to be driven by diesel buses or by the installed diesel auxiliary engine
- Unidirectional power supply from the medium voltage network

The aim of the project "BOB Solingen" is to electrify public transport





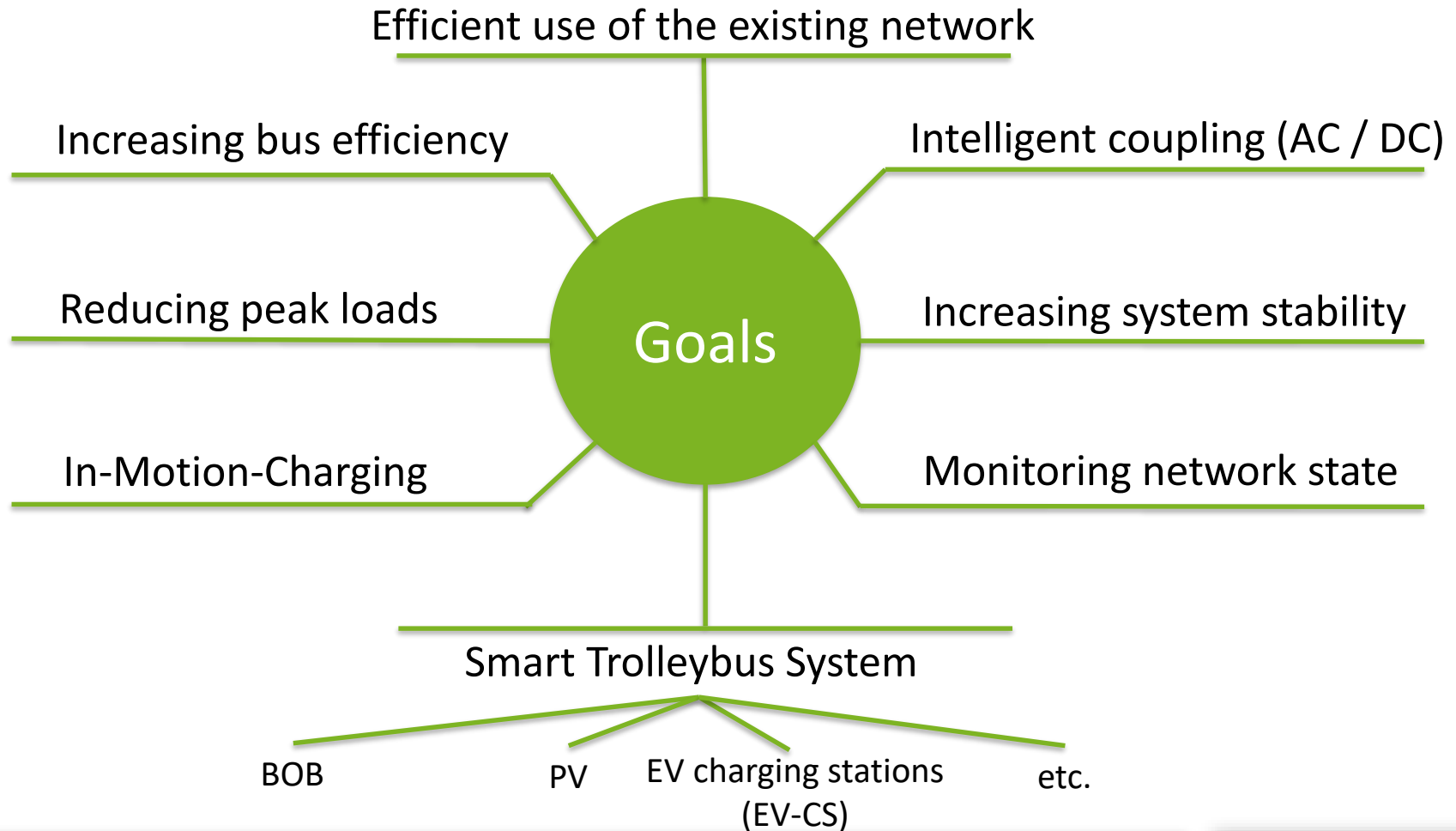
# Project „BOB Solingen“

Gefördert durch:



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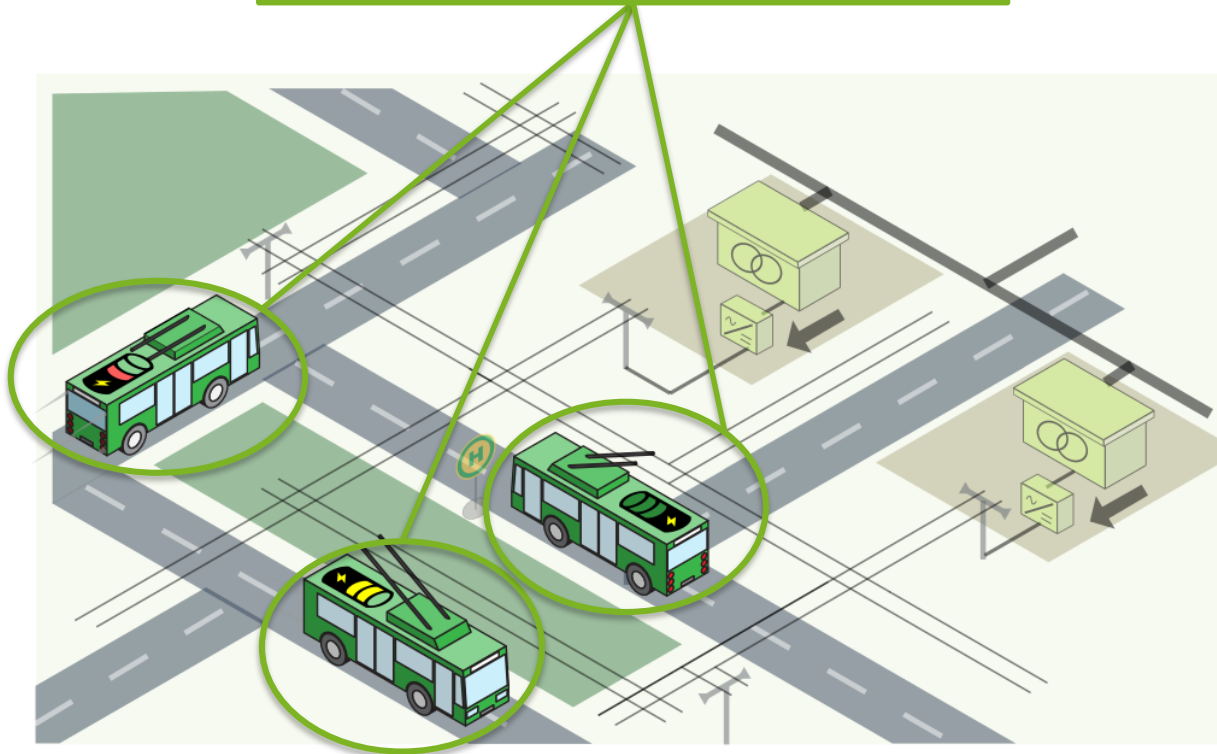


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## Battery-Trolleybuses (BOB)





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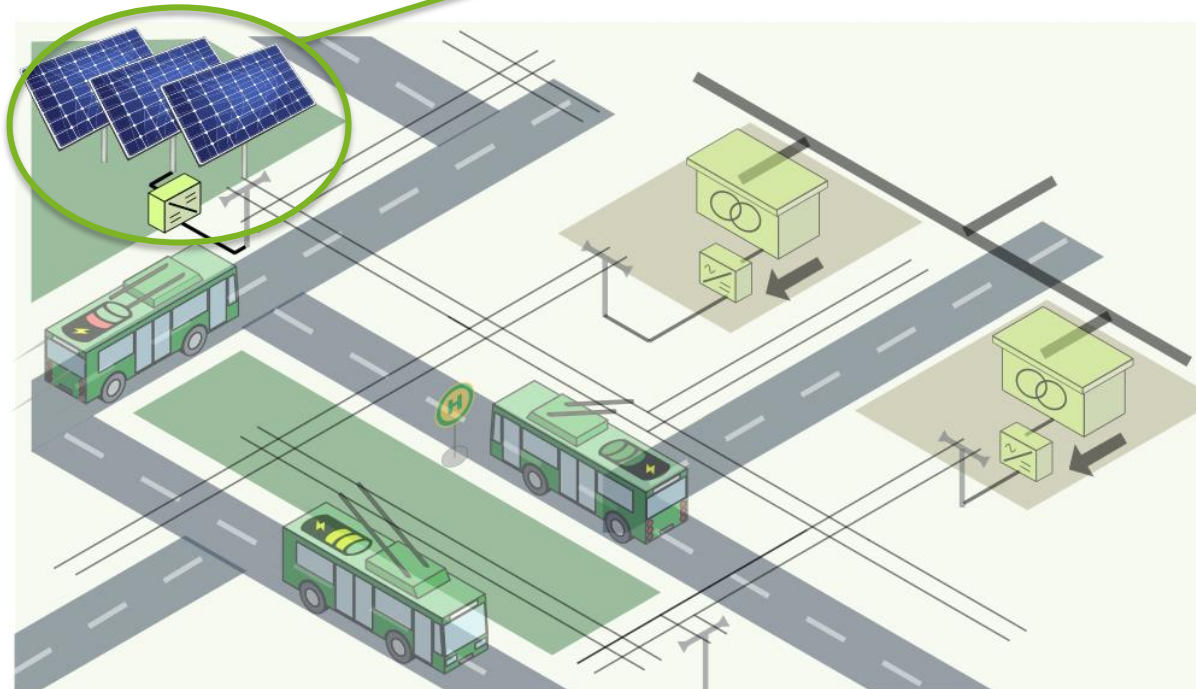


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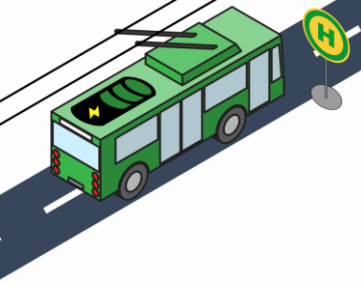
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## Photovoltaic Systems







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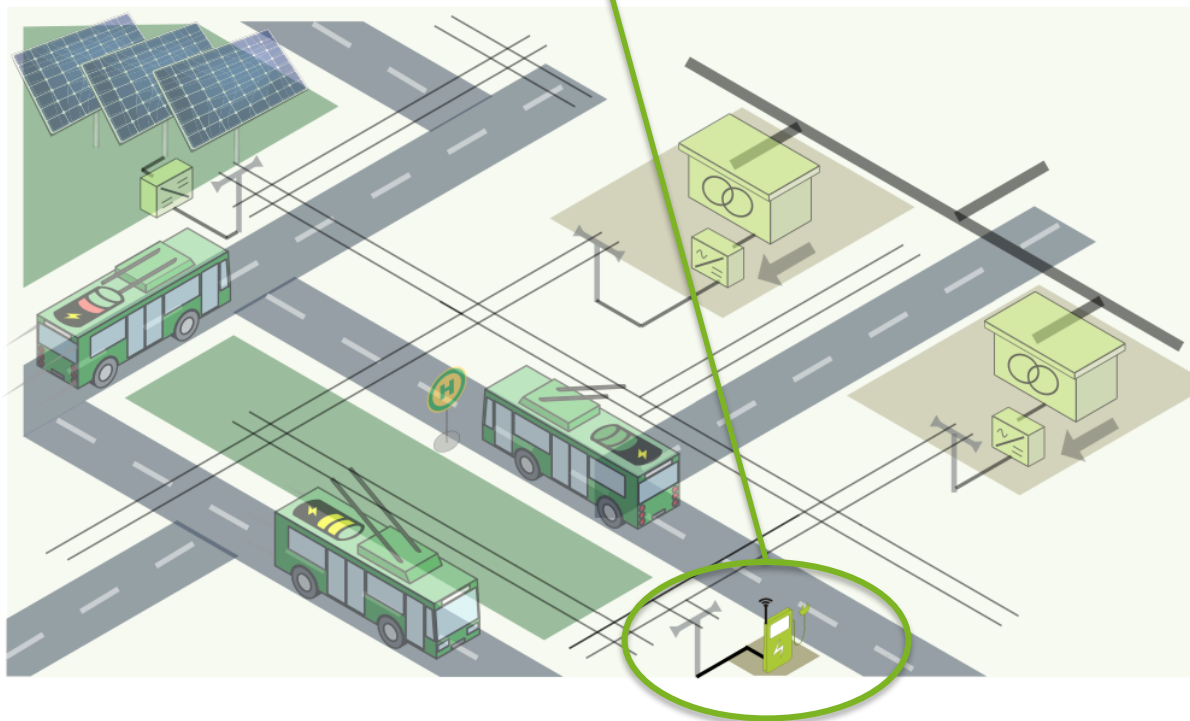


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## Charging Stations for Electric Vehicles







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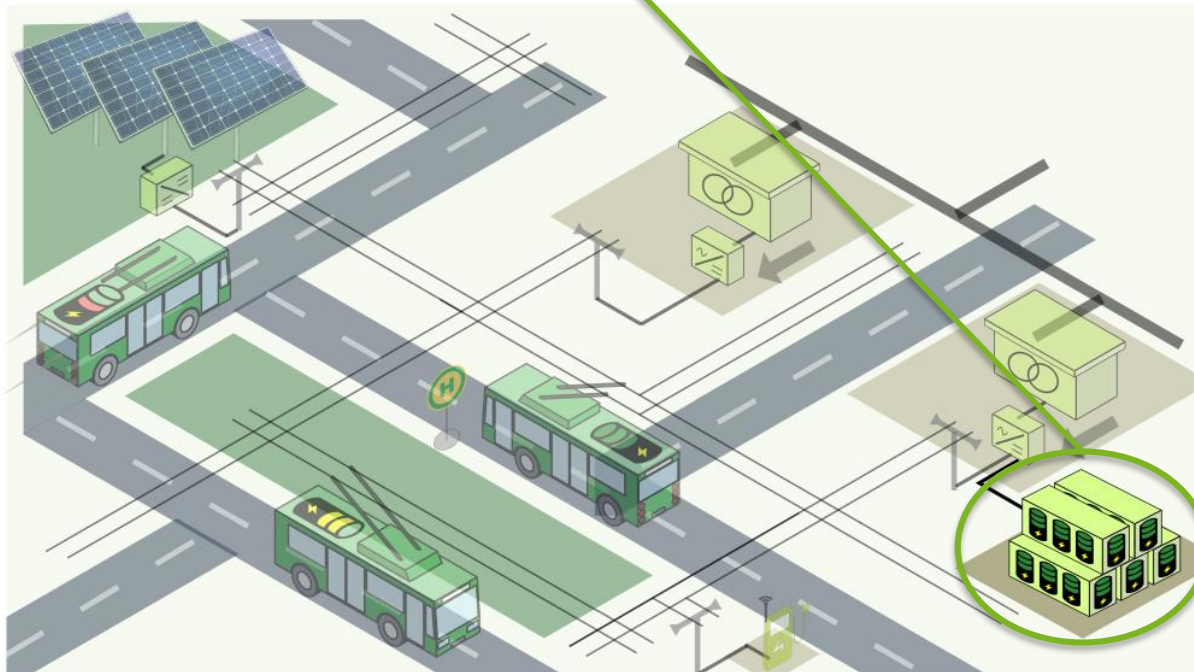


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## Stationary Storage





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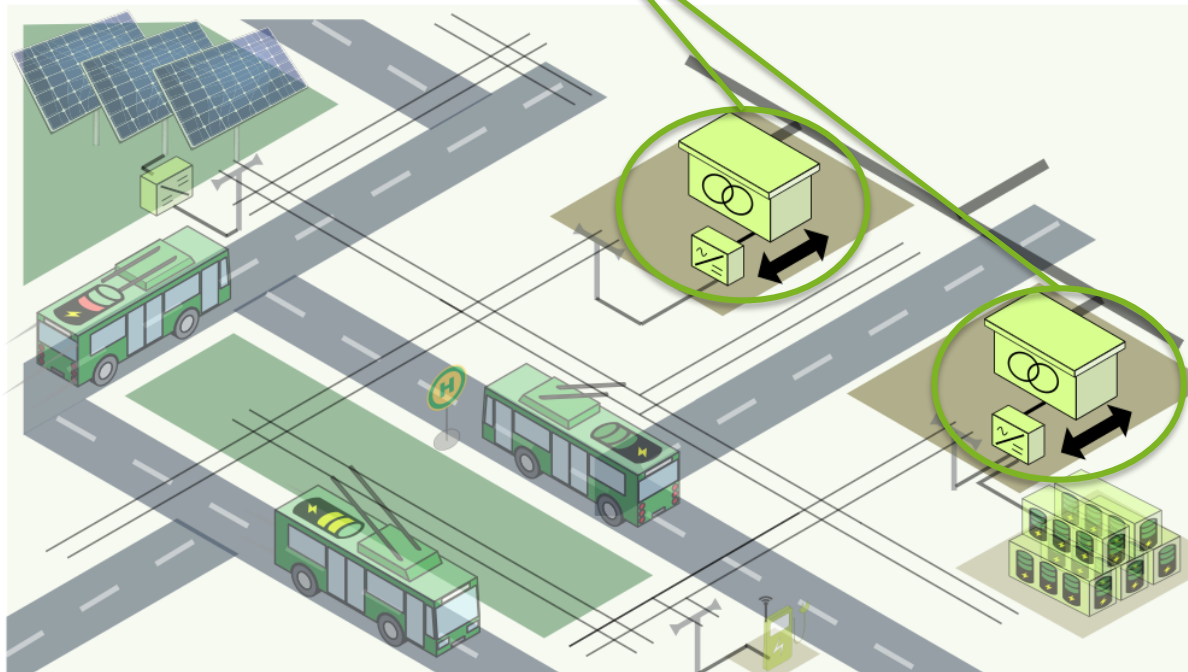


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## Bidirectional Substations





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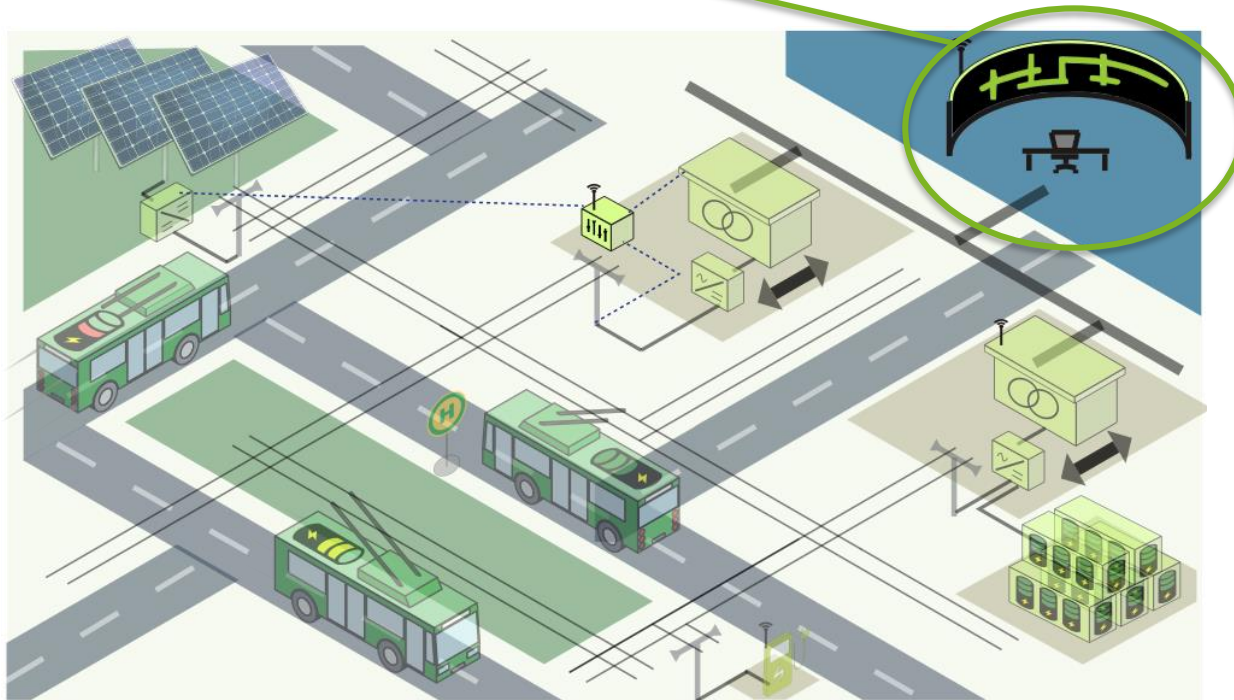


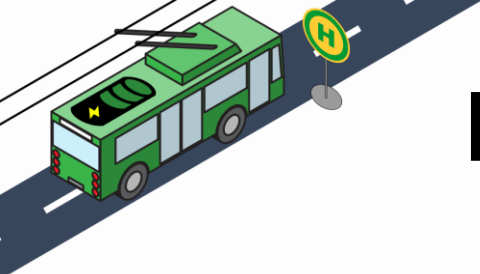
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## Intelligent Grid Control





# Project „BOB Solingen“

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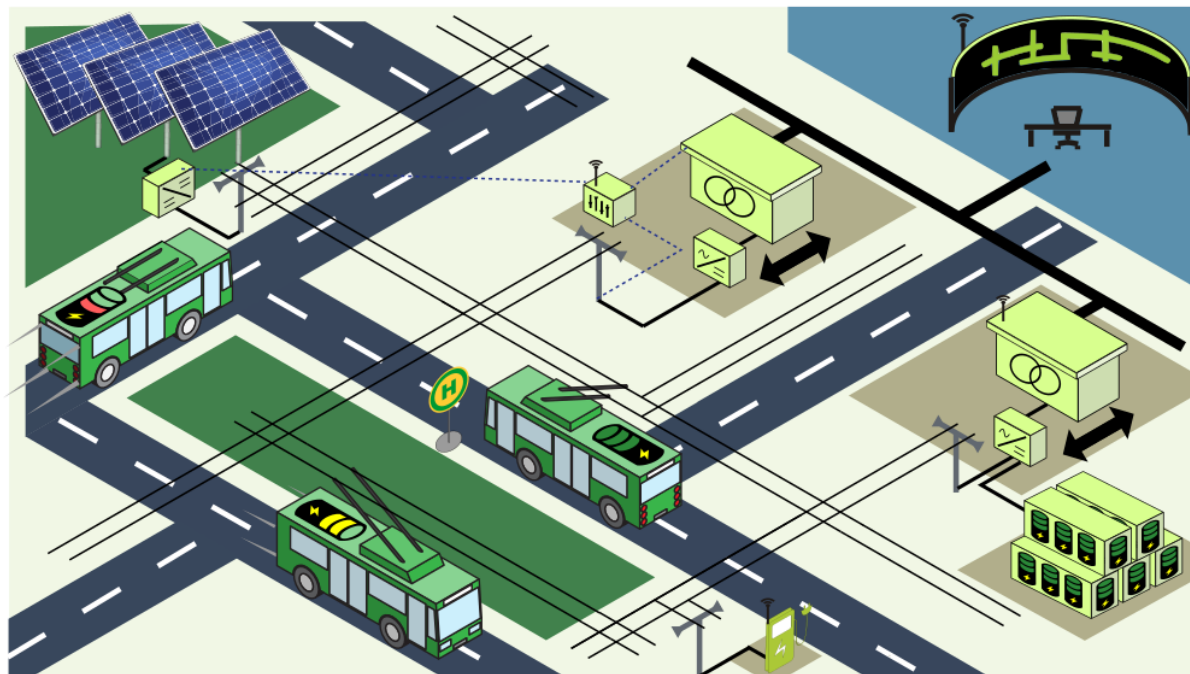


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Koordiniert durch:



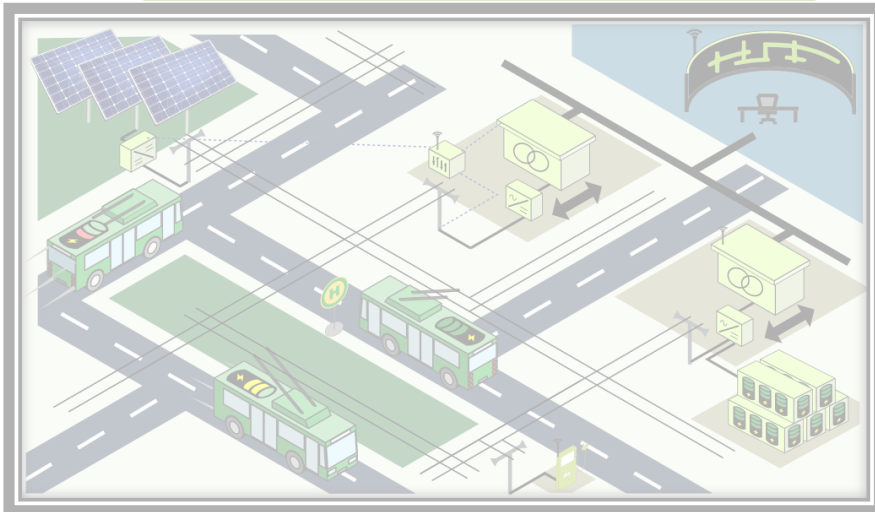
## Future State



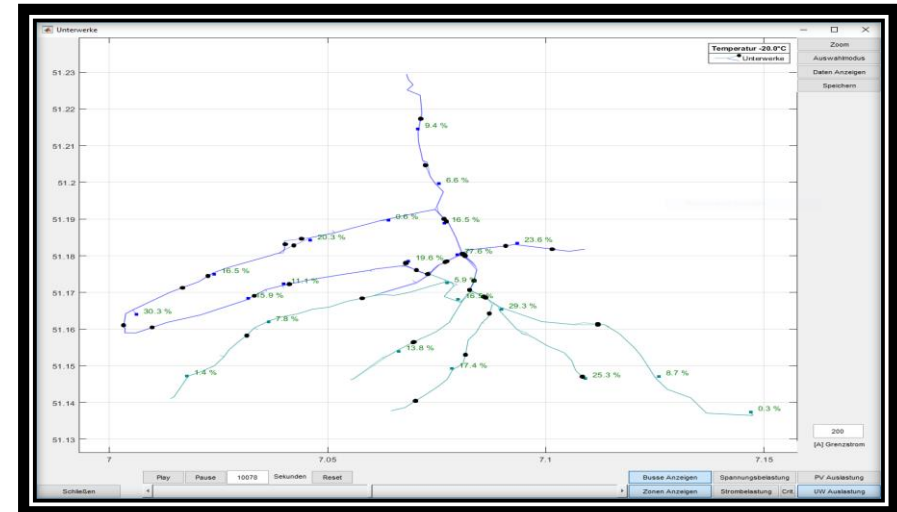


# Structure

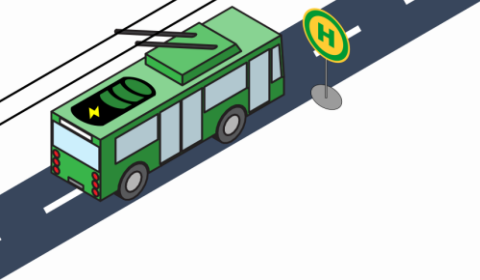
## Status Quo & Project “BOB Solingen”



## Goal Realization







# Goal Realization

## Step 1: Simulation

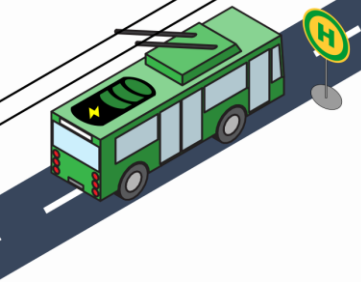
- Realistic modeling of the individual components and the overall system
- Optimal locations for new components (PV, charging stations for electric vehicles, stat. storage and bidirectional substations)

## Step 2: Monitoring

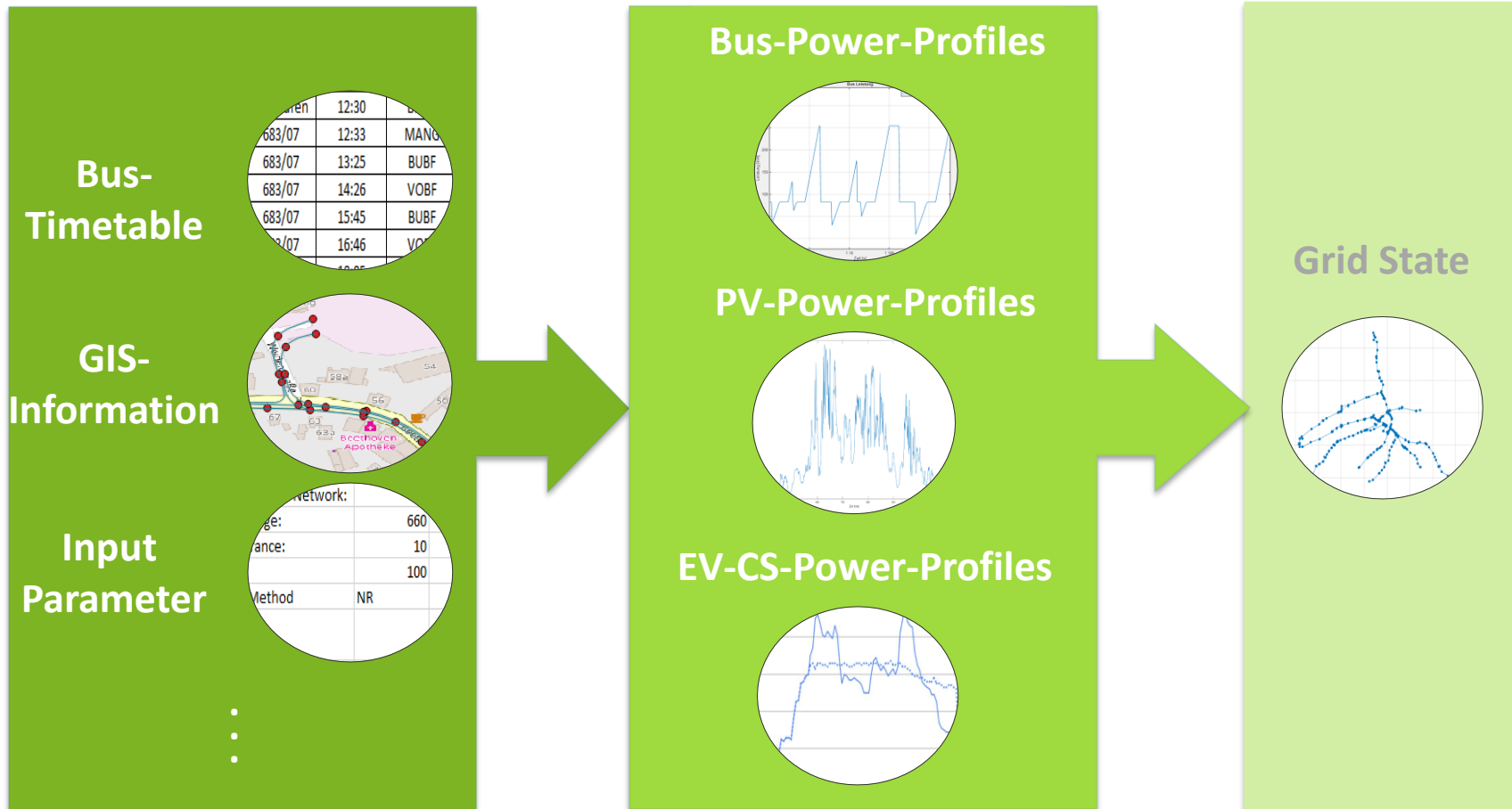
- Estimate / determine network state
- Recognize critical network states

## Step 3: Controlling

- Controlling the actuators in the network to eliminate or prevent critical network states



# Simulation







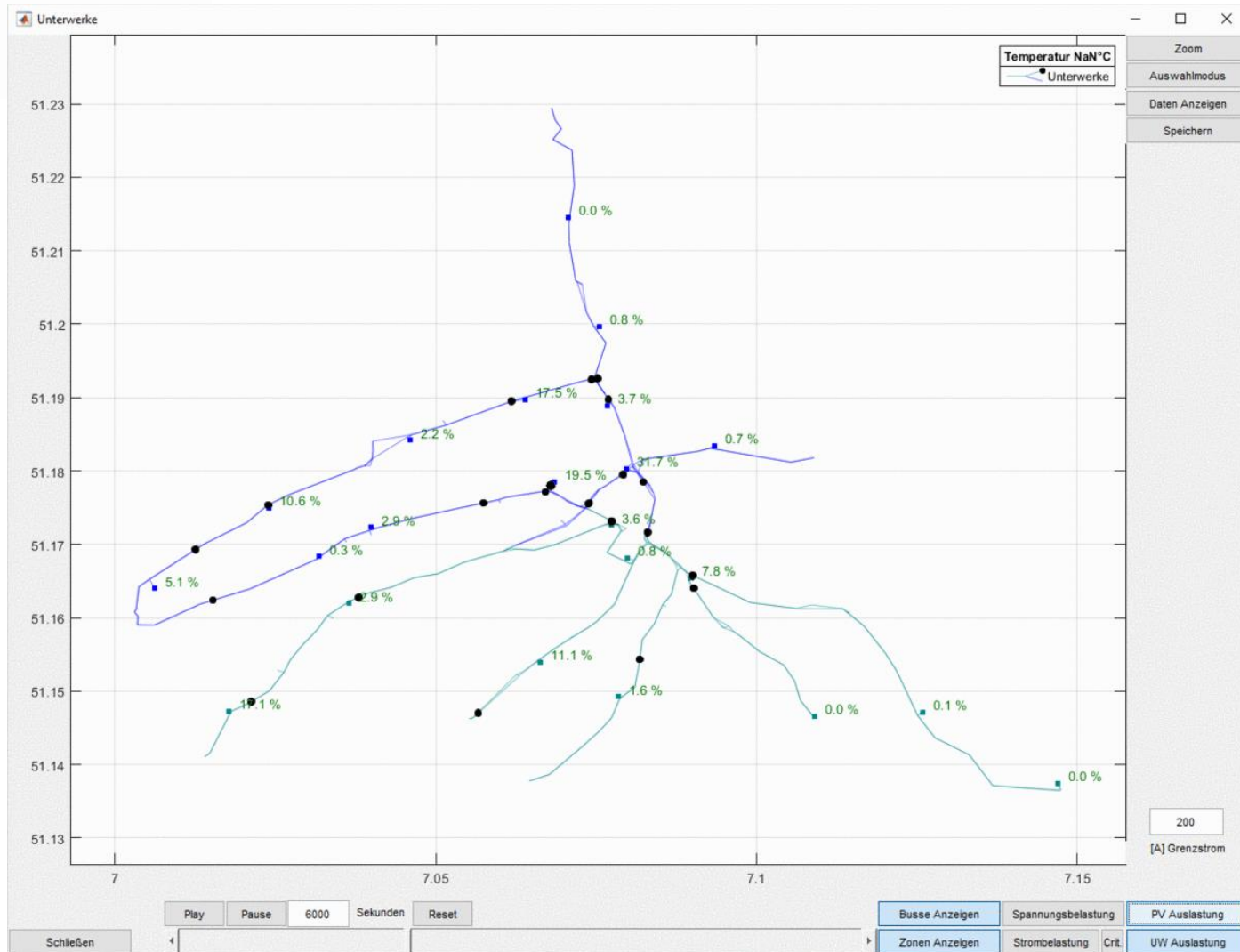
# Simulation

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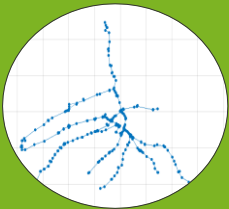
Koordiniert durch:





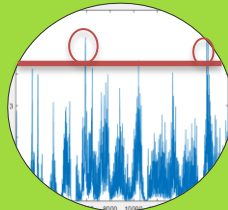
# Monitoring & Controlling

## Grid State



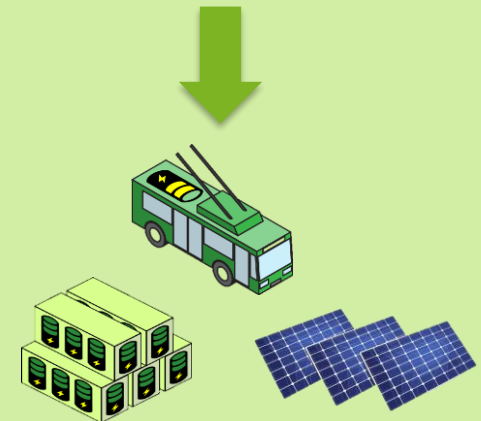
## Monitoring

- Check the availability of measured values
- Estimate missing values
- Detection of limit violations



## Controlling

- Controlling the actuators to eliminate the limit violations



Thank you for your Attention!  
Questions?



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